

Machine Learning I

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Deciding with Binary Decision Trees

Contents. This part of the course is about a special case of supervised learning: the supervised learning of binary decision trees.

- ▶ We state the problem by defining labeled data, a family of functions, a regularizer and a loss function
- ▶ We prove that the problem is hard to solve (technically: NP-hard), by relating it to the exact cover by 3-sets problem.

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Data

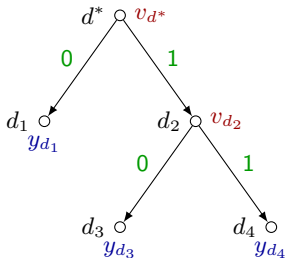
We consider binary attributes. More specifically, we consider some finite, non-empty set V , called the set of attributes, and labeled data $T = (S, X, x, y)$ such that $X = \{0, 1\}^V$.

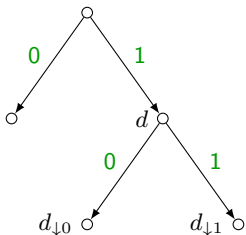
Hence, $x: S \rightarrow \{0, 1\}^V$ and $y: S \rightarrow \{0, 1\}$.

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Definition. A tuple $(V, Y, D, D', d^*, E, \delta, v, y)$ is called a V -variate Y -valued **binary decision tree** (BDT) iff the following conditions hold:

1. $V \neq \emptyset$ is finite (set of **variables**)
2. $Y \neq \emptyset$ is finite (set of **values**)
3. $(D \cup D', E)$ is a finite, non-empty directed binary tree with root d^*
4. every $d \in D'$ is a leaf
5. $\delta: E \rightarrow \{0, 1\}$
6. every $d \in D$ has precisely two out-edges, $e = (d, d')$, $e' = (d, d'')$, such that $\delta(e) = 0$ and $\delta(e') = 1$
7. $v: D \rightarrow V$
8. $y: D' \rightarrow Y$





Definition. For any BDT $(V, Y, D, D', d^*, E, \delta, v, y)$, any $d \in D$ and any $j \in \{0, 1\}$, we let $d_{\downarrow j} \in D \cup D'$ the unique node such that $e = (d, d_{\downarrow j}) \in E$ and $\delta(e) = j$.

Definition. For any BDT $\theta = (V, Y, D, D', d^*, E, \delta, v, y)$ and any $d \in D \cup D'$, the tuple $\theta[d] = (V, Y, D_2, D'_2, d, E', \delta', v', y')$ is called the **binary decision subtree** of θ rooted at d iff

- ▶ $(D_2 \cup D'_2, E')$ is the subtree of $(D \cup D', E)$ rooted at d
- ▶ δ', v' and y' are the restrictions of δ, v and y to the subsets D_2, D'_2 and E'

Lemma. For any BDT $\theta = (V, Y, D, D', d^*, E, \delta, v, y)$ and any $d \in D \cup D'$, the binary decision subtree $\theta[d]$ is itself a V -variate Y -valued BDT.

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Definition. For any BDT $\theta = (V, Y, D, D', d^*, E, \delta, v, y)$, the function defined by θ is the $f_\theta : \{0, 1\}^V \rightarrow Y$ such that $\forall x \in \{0, 1\}^V$:

$$\begin{aligned} f_\theta(x) &= \begin{cases} y(d^*) & \text{if } D = \emptyset \\ f_{\theta[d_{\downarrow 0}^*]}(x) & \text{if } D \neq \emptyset \wedge x_{v(d^*)} = 0 \\ f_{\theta[d_{\downarrow 1}^*]}(x) & \text{if } D \neq \emptyset \wedge x_{v(d^*)} = 1 \end{cases} \\ &= \begin{cases} y(d^*) & \text{if } D = \emptyset \\ (1 - x_{v(d^*)})f_{\theta[d_{\downarrow 0}^*]}(x) + x_{v(d^*)}f_{\theta[d_{\downarrow 1}^*]}(x) & \text{otherwise} \end{cases} \end{aligned}$$

Note. The set Θ of V -variate $Y = \{0, 1\}$ -valued BDTs can be identified with a subset of V -variate DNFs.

Regularization

In order to quantify the complexity of BDTs, we consider the following regularizer.

Definition. For any BDT $\theta = (V, Y, D, D', d^*, E, \delta, v, y)$, the **depth** of θ is the $R(\theta) \in \mathbb{N}$ such that

$$R(\theta) = \begin{cases} 0 & \text{if } D = \emptyset \\ 1 + \max\{R(\theta[d_{\downarrow 0}^*]), R(\theta[d_{\downarrow 1}^*])\} & \text{otherwise} \end{cases} . \quad (1)$$

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Loss function

We consider the **0/1-loss** L , i.e.

$$\forall r \in \mathbb{R} \forall \hat{y} \in \{0, 1\}: \quad L(r, \hat{y}) = \begin{cases} 0 & r = \hat{y} \\ 1 & \text{otherwise} \end{cases} . \quad (2)$$

Definition. For any $\lambda \in \mathbb{R}_0^+$, the instance of the **supervised learning problem of BDTs** with respect to T, L, R and λ has the form

$$\min_{\theta \in \Theta} \lambda R(\theta) + \frac{1}{|S|} \sum_{s \in S} L(f_\theta(x_s), y_s) \quad (3)$$

Definition. For any $m \in \mathbb{N}$, the **bounded depth BDT problem** w.r.t. T and m is to decide whether there exists a BDT $\theta = (V, Y, D, D', d^*, E, \delta, v, y')$ such that

$$R(\theta) \leq m \quad (4)$$

$$\forall s \in S: f_\theta(x_s) = y_s \quad (5)$$

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Next, we will reduce the hard-to-solve (technically: NP-hard) exact cover by 3-sets problem to the bounded depth BDT problem, thereby showing that the latter problem is hard to solve (NP-hard) as well. The reduction is by Haussler (1988).

Definition. For any set S , a cover Σ of S is called **exact** iff the elements of Σ are pairwise disjoint.

Definition. Let S be any set, and let $\emptyset \notin \Sigma \subseteq 2^S$.

Deciding whether there exists a $\Sigma' \subseteq \Sigma$ such that Σ' is an exact cover of S is called the instance of the **exact cover problem** w.r.t. S and Σ .

Additionally, if $|S|$ is an integer multiple of three and any $U \in \Sigma$ is such that $|U| = 3$, the instance of the exact cover problem w.r.t. S and Σ is also called the instance of the **exact cover by 3-sets problem** with respect to S and Σ .

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Proof. For any instance (S', Σ) of the exact cover by 3-sets problem and the $n \in \mathbb{N}$ such that $|S'| = 3n$, we construct the instance of the m -bounded depth BDT problem such that

- ▶ $V = \Sigma$
- ▶ $S = S' \cup \{0\}$
- ▶ $x : S \rightarrow \{0, 1\}^\Sigma$ such that $x_0 = 0$ and

$$\forall s \in S' \forall \sigma \in \Sigma: \quad x_s(\sigma) = \begin{cases} 1 & \text{if } s \in \sigma \\ 0 & \text{otherwise} \end{cases} \quad (6)$$

- ▶ $y : S \rightarrow \{0, 1\}$ such that $y_0 = 0$ and $\forall s \in S' : y_s = 1$.
- ▶ $m = n$

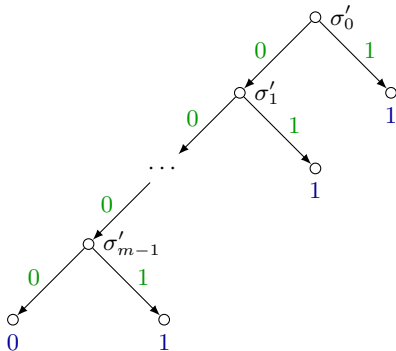
We show that the instance the exact cover problem has a solution iff the instance of the bounded depth BDT problem has a solution.

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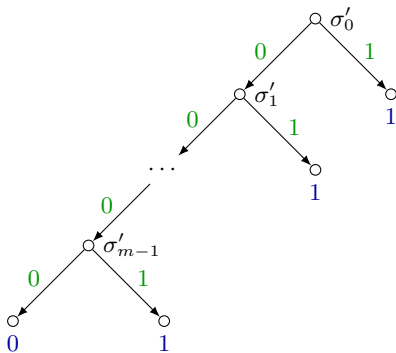
(\Rightarrow) Let $\Sigma' \subseteq \Sigma$ a solution to the instance of the exact cover problem.

Consider any order on Σ' and the bijection $\sigma' : [n] \rightarrow \Sigma'$ induced by this order.

We show that the BDT θ depicted below solves the instance of the bounded depth BDT problem.



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The BDT satisfies $R(\theta) = m$.

The BDT decides the labeled data correctly because

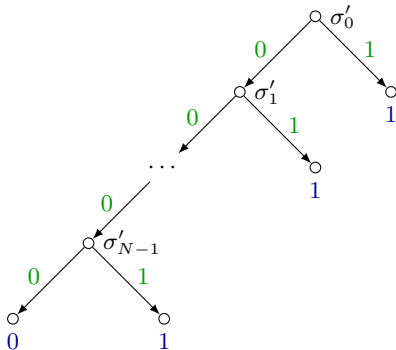
- ▶ $f_\theta(x_0) = 0 = y_0$
- ▶ At each of the m interior nodes, three additional elements of S' are mapped to 1. Thus, all $3m$ many elements $s \in S'$ are mapped to 1. That is $\forall s \in S': f_\theta(x_s) = 1 = y_s$.

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(\Leftarrow) Let $\theta = (V, Y, D, D', d^*, E, \delta, \sigma, y')$ a BDT that solves the instance of the bounded depth BDT problem.

W.l.o.g., we assume, for any interior node $d \in D$, that $d_{\downarrow 1}$ is a leaf and $y'(d_{\downarrow 1}) = 1$.

Hence, θ is of the form depicted below.



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Therefore:

$$\forall x \in X: f_{\theta}(x) = \begin{cases} 1 & \text{if } \exists j \in [N]: x(\sigma_j) = 1 \\ 0 & \text{otherwise} \end{cases} \quad (7)$$

Thus,

$$\forall s \in S: f_{\theta}(x_s) = \begin{cases} 1 & \text{if } \exists j \in [N]: s \in \sigma_j \\ 0 & \text{otherwise} \end{cases}, \quad (8)$$

by definition of x in (6).

Consequently,

$$\bigcup_{j=0}^{N-1} \sigma_j = S', \quad (9)$$

by definition of y such that $\forall s \in S': y_s = 1$.

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Moreover, $N = m$, because

$$3m = |S'| \stackrel{(9)}{=} \left| \bigcup_{j=0}^{N-1} \sigma_j \right| \leq \sum_{j=0}^{N-1} |\sigma_j| = \sum_{j=0}^{N-1} 3 = 3N \stackrel{(4)}{\leq} 3m .$$

Therefore:

$$\forall \{j, l\} \in \binom{[N]}{2}: \quad \sigma_j \cap \sigma_l = \emptyset \quad (10)$$

Thus,

$$\bigcup_{j=0}^{N-1} \sigma_j$$

is a solution to the instance of the exact cover by 3-sets problem defined by (S', Σ) , by (9) and (10).

□

Summary:

- ▶ BDTs can be identified with a subset of DNFs.
- ▶ Supervised learning of BDTs is hard. More specifically, the NP-hard exact cover by 3-sets problem is reducible to the bounded depth BDT problem by construction of Hausler data.

Further reading: Readers who are not familiar with the exact cover by 3-sets problem or the set cover problem will find proofs of their NP-hardness in Appendices A.1–A.4 of the lecture notes.